

Synchronisation

Daniel Bosk¹

Department of Information and Communication Systems (ICS),
Mid Sweden University, Sundsvall.

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Overview

- 1 Synchronisation
 - Where does the problem arise?
 - The Critical-Section Problem
 - Tools to solve the problem

- 2 Deadlocks
 - The requirements
 - Dining Philosophers Problem

Literature

This lecture covers the second half of the topic process management. It gives an overview of Chapter 5 “Process Synchronization” and Chapter 7 “Deadlocks” in [SGG13a; SGG13b], or Chapter 6 “Synchronization” and Chapter 7 “Deadlocks” in [SGG09].

Overview

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Where does the problem arise?

```
1 i = 0
2 while (True):
3     i = i + 1
```

Where does the problem arise?

- When we have a preemptive scheduler or multiprocessor system, multiple processes can try to use the same resource at the same time.
- When the outcome of the execution depends on the order of execution of the processes we say we have a race condition.

The Critical-Section Problem

- We can sort out the parts of the code of a program which are susceptible to race conditions, these parts are called the critical sections.
- The code just before the critical section is called the entry section.
- The code in the end of the critical section is the exit section.
- The code after the critical section is the remainder section.
- The Critical-Section Problem is about the design of a protocol for several processes to use for cooperation around their critical sections.

The Critical-Section Problem

To solve the Critical-Section Problem an algorithm (protocol) must fulfill the following requirements:

- ① Mutual exclusion. If a process P_i is executing in its critical section, no other process may do so.
- ② Progress. If no process is executing in its critical section and some processes wish to enter their critical sections, then only those processes *not* in their remainder sections can participate in the decision.
- ③ Bounded waiting. There exists a bound for how long a process which has requested to enter its critical section may have to wait before allowed to enter.

Tools to solve the problem

- Peterson's solution.
- Locks.
- Semaphores.

Tools to solve the problem

Peterson's Solution

```
1 while (True):
2     flag[i] = True
3     turn = j
4     while ( flag[j] and turn == j ):
5         pass
6
7     # critical section
8
9     flag[i] = False
10
11    # remainder section
```

Tools to solve the problem

- On modern computer architectures we need special hardware instructions to help us, e.g. TestAndSet or AtomicSwap.

Tools to solve the problem

TestAndSet

```
1 # lock = [False]
2 while ( True ):
3     while ( TestAndSet( lock ) ):
4         pass
5
6     # critical section
7
8     lock = False
9
10    # remainder section
```

Tools to solve the problem

AtomicSwap

```
1 # lock = [False]
2 while ( True ):
3     key = [True]
4     while ( key[0] ):
5         AtomicSwap( lock, key )
6
7     # critical section
8
9     lock = False
10
11    # remainder section
```

Tools to solve the problem I

Bounded waiting

```
1 # lock = [False]
2 while ( True ):
3     waiting[i] = True
4     key = True
5     while ( waiting[i] and key[0] ):
6         key = TestAndSet( lock ) )
7
8     waiting[i] = False
9
10    # critical section
11
12    j = ( i + 1 ) \% n
13    while ( ( j != i ) and not waiting[j] ):
14        j = ( j + 1 ) \% n
15
16    if ( j == i ):
```



Tools to solve the problem II

Bounded waiting

```
17     lock = False
18 else:
19     waiting[j] = False
20
21     # remainder section
```

Tools to solve the problem

Semaphores

- Use two operations `wait()` and `signal()`.
- A binary valued semaphore is called a mutex lock, since it provides mutual exclusion.
- We have also counting semaphores.

Tools to solve the problem

Semaphores

```
1 def wait( S ):
2     while ( S <= 0 ):
3         pass
4     S -= 1
```

```
1 def signal( S ):
2     S += 1
```

Tools to solve the problem

Semaphores

```
1 while ( True ):  
2     wait( mutex )  
3  
4     # critical section  
5  
6     signal( mutex )  
7  
8     # remainder section
```

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The requirements

For a deadlock to occur, the following requirements must be fulfilled:

- ① Mutual exclusion.
- ② Hold and wait.
- ③ No preemption.
- ④ Circular wait.

The converse, to prevent deadlocking we must guarantee at least one of the above requirements is not fulfilled at any time.

The requirements

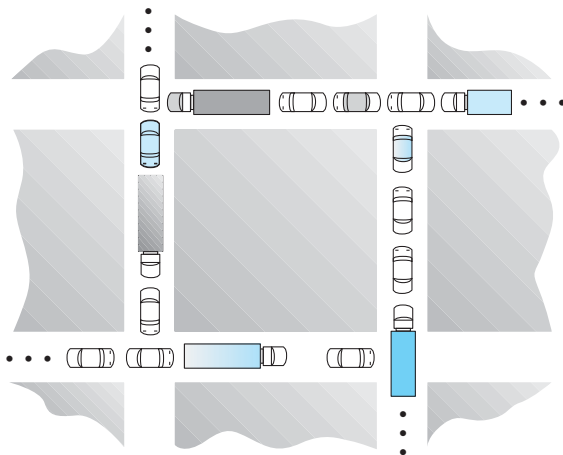


Figure: A deadlock. Image: [SGG13b].

The requirements

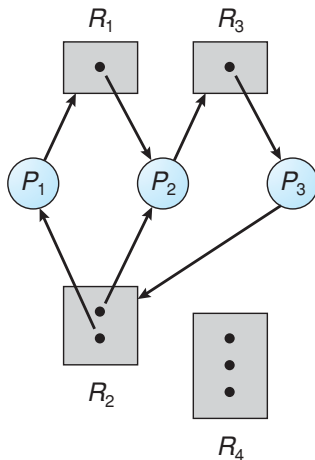


Figure: Another deadlock. Image: [SGG13b].

The requirements

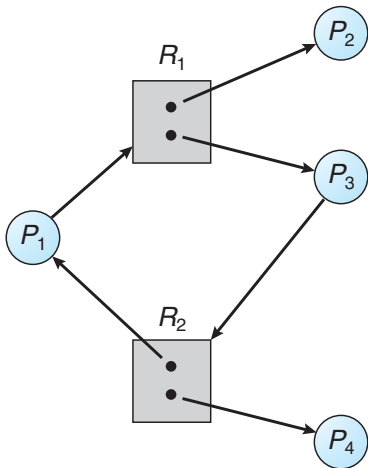


Figure: A similar situation which is not a deadlock. Image: [SGG13b].

Dining Philosophers Problem

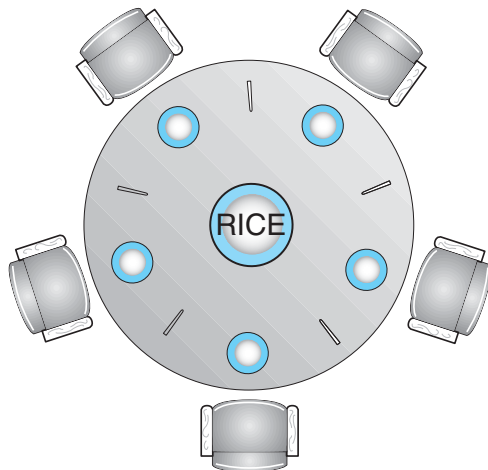


Figure: The setup of the Dining Philosophers Problem. Image: [SGG13b].

Referenser I



Abraham Silberschatz, Peter Baer Galvin, and Greg Gagne. *Operating System Concepts*. 8th ed. International Student Version. Hoboken, N.J.: John Wiley & Sons Inc, 2009.



Abraham Silberschatz, Peter Baer Galvin, and Greg Gagne. *Operating System Concepts*. 9th ed. International Student Version. Hoboken, N.J.: John Wiley & Sons Inc, 2013.



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